

General Certificate of Education (A-level)
June 2011

Mathematics

MM04

(Specification 6360)

Mechanics 4

Final

Mark Scheme

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Key to mark scheme abbreviations

M	mark is for method
m or dM	mark is dependent on one or more M marks and is for method
A	mark is dependent on M or m marks and is for accuracy
В	mark is independent of M or m marks and is for method and accuracy
E	mark is for explanation
√or ft or F	follow through from previous incorrect result
CAO	correct answer only
CSO	correct solution only
AWFW	anything which falls within
AWRT	anything which rounds to
ACF	any correct form
AG	answer given
SC	special case
OE	or equivalent
A2,1	2 or 1 (or 0) accuracy marks
–x EE	deduct x marks for each error
NMS	no method shown
PI	possibly implied
SCA	substantially correct approach
c	candidate
sf	significant figure(s)
dp	decimal place(s)

No Method Shown

Where the question specifically requires a particular method to be used, we must usually see evidence of use of this method for any marks to be awarded.

Where the answer can be reasonably obtained without showing working and it is very unlikely that the correct answer can be obtained by using an incorrect method, we must award **full marks**. However, the obvious penalty to candidates showing no working is that incorrect answers, however close, earn **no marks**.

Where a question asks the candidate to state or write down a result, no method need be shown for full marks.

Where the permitted calculator has functions which reasonably allow the solution of the question directly, the correct answer without working earns **full marks**, unless it is given to less than the degree of accuracy accepted in the mark scheme, when it gains **no marks**.

Otherwise we require evidence of a correct method for any marks to be awarded.

MM04

The image of the	Q	Solution	Marks	Total	Comments
(b) $ \mathbf{r}_{1} \times \mathbf{F}_{1} = \begin{vmatrix} \mathbf{i} & 0 & -1 \\ \mathbf{j} & 2 & 1 \\ \mathbf{k} & 1 & 0 \end{vmatrix} = \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} $ $ \mathbf{r}_{2} \times \mathbf{F}_{2} = \begin{vmatrix} \mathbf{i} & 3 & 4 \\ \mathbf{j} & -1 & 0 \\ \mathbf{k} & 0 & -2 \end{vmatrix} = \begin{pmatrix} 2 \\ 6 \\ 4 \end{pmatrix} $ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix} $ $ \mathbf{n}_{1} $ $ \mathbf{n}_{2} \times \mathbf{n}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{i} & 4 & -3 \\ \mathbf{i} & 4 & -3 \\ \mathbf{i} & 4 & -4 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix} $ $ \mathbf{n}_{1} $ $ \mathbf{n}_{2} \times \mathbf{n}_{3} = \mathbf{n}_{3} = \mathbf{n}_{4} $ $ \mathbf{n}_{2} \times \mathbf{n}_{3} = \mathbf{n}_{4} = \mathbf{n}_{4} $ $ \mathbf{n}_{3} \times \mathbf{n}_{3} = \mathbf{n}_{4} = \mathbf{n}_{4} $ $ \mathbf{n}_{4} \times \mathbf{n}_{5} = \mathbf{n}_{5} = \mathbf{n}_{5} $ $ \mathbf{n}_{5} \times \mathbf{n}_{5} = \mathbf{n}_{5} = \mathbf{n}_{5} $ $ \mathbf{n}_{6} \times \mathbf{n}_{7} = \mathbf{n}_{7} = \mathbf{n}_{7} = \mathbf{n}_{7} $ $ \mathbf{n}_{1} \times \mathbf{n}_{1} = \mathbf{n}_{7} = \mathbf{n}_{7}$			wial NS	Tutai	Comments
$ \mathbf{r}_{1} \times \mathbf{F}_{1} = \begin{vmatrix} \mathbf{j} & 2 & 1 \\ \mathbf{k} & 1 & 0 \end{vmatrix} = \begin{vmatrix} -1 \\ 2 \end{vmatrix}$ $ \mathbf{r}_{2} \times \mathbf{F}_{2} = \begin{vmatrix} \mathbf{i} & 3 & 4 \\ \mathbf{j} & -1 & 0 \\ \mathbf{k} & 0 & -2 \end{vmatrix} = \begin{pmatrix} 2 \\ 6 \\ 4 \end{pmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{vmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{vmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{j} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{vmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{j} & 4 & -3 \\ 4 & 12 \\ 2 \end{vmatrix}$ $ \mathbf{r}_{3} \times \mathbf{F}_{4} = \begin{vmatrix} \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} &$	1(a)	$\begin{pmatrix} -1\\1\\0 \end{pmatrix} + \begin{pmatrix} 4\\0\\-2 \end{pmatrix} + \begin{pmatrix} -3\\-1\\2 \end{pmatrix} = \begin{pmatrix} 0\\0\\0 \end{pmatrix}$	B1	1	Clear use of $\sum \mathbf{F}_i = 0$
$\mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix}$ $A3,2,1$ $\begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix} + \begin{pmatrix} 2 \\ 6 \\ 4 \end{bmatrix} + \begin{pmatrix} -5 \\ 7 \\ -4 \end{bmatrix} = \begin{pmatrix} -4 \\ 12 \\ 2 \end{pmatrix}$ $Resultant force = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \text{ and moment about}$ $A3,2,1$		$\mathbf{r}_1 \times \mathbf{F}_1 = \begin{vmatrix} \mathbf{j} & 2 & 1 \\ \mathbf{k} & 1 & 0 \end{vmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$	M1		Any attempt at $\mathbf{r} \times \mathbf{F}$ or $\mathbf{F} \times \mathbf{r}$
$\begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \\ 4 \end{pmatrix} + \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix} = \begin{pmatrix} -4 \\ 12 \\ 2 \end{pmatrix}$ $\begin{pmatrix} \mathbf{m1} \\ \mathbf{A1F} \\ 2 \end{pmatrix}$ $\begin{pmatrix} 6 \\ \mathbf{F} \\ \mathbf$					
$\begin{vmatrix} -1 \\ 2 \end{vmatrix} + \begin{vmatrix} 6 \\ 4 \end{vmatrix} + \begin{vmatrix} 7 \\ -4 \end{vmatrix} = \begin{vmatrix} 12 \\ 2 \end{vmatrix}$ $\begin{vmatrix} 12 \\ 2 \end{vmatrix}$ Resultant force = $\begin{vmatrix} 0 \\ 0 \end{vmatrix}$ and moment about $\begin{vmatrix} 12 \\ 2 \end{vmatrix}$ $\begin{vmatrix} 12 \\ 2 $		$\mathbf{r}_3 \times \mathbf{F}_3 = \begin{vmatrix} \mathbf{i} & 4 & -3 \\ \mathbf{j} & 0 & -1 \\ \mathbf{k} & -5 & 2 \end{vmatrix} = \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix}$	A3,2,1		-1 each 'type' of error
Resultant force = $\begin{vmatrix} 0 \end{vmatrix}$ and moment about $\begin{vmatrix} E2.1 \end{vmatrix}$ $\begin{vmatrix} E1 \end{vmatrix}$ $\sum \mathbf{F} = 0$		$ \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \\ 4 \end{pmatrix} + \begin{pmatrix} -5 \\ 7 \\ -4 \end{pmatrix} = \begin{pmatrix} -4 \\ 12 \\ 2 \end{pmatrix} $		6	Follow through their three answers for $\mathbf{r} \times \mathbf{F}$
O is non zero \Rightarrow couple	(c)	(0)	E2,1	2	E1 $\sum \mathbf{F} = 0$ E1 Moment $\neq 0$
Total 9		Total		9	

Q Q	Solution	Marks	Total	Comments
2(a)	Volume of cone = $\frac{1}{3}\pi r^2 h = \frac{8h^3\pi}{3}$	B1		Correct volume
	Alternative: $\left[\pi \int_{0}^{8h} \left(\frac{1}{8} x \right)^{2} dx = \frac{8h^{3}}{3} \pi \right]$	(B1)		
	$\pi \int xy^2 dx = \pi \int_0^{8h} x \left(\frac{x}{8}\right)^2 dx = \pi \int_0^{8h} \frac{x^3}{64} dx$	M1		Use of $\int xy^2 dx$
	$= \int_{0}^{8h} \left[\frac{x^4}{256} \right]$ $= 16h^4$	A1		Correct integration of kx^3
	$\overline{x} = \frac{\pi \int xy^2 dx}{\pi \int y^2 dx} = \frac{16h^4 \pi}{8h^3 \frac{\pi}{2}}$	M1		Attempt at formula for \overline{x}
	=6h	A1	5	AG
(b)(i)	R	B1		3 forces
	F W	B1	2	Through a common point at base of cone
(ii)	G above point of rotation			
	$\tan \theta = \frac{r}{d}$	M1		$\tan \theta$ seen anywhere
	$=\frac{h}{8h-6h}=\frac{1}{2}$	A1		Ratio correct
	$\theta = \tan^{-1} \frac{1}{2} = 26.6^{\circ}$	A1F	3	Use of \tan^{-1} to get θ ; ft incorrect ratio
(c)	Resolve perp to plane $N = W \cos \alpha$ parallel to plane $F = W \sin \alpha$	B1		Both correct
	Limiting friction $F = \mu N \Rightarrow \tan \alpha = \frac{6}{13}$	M1		Eliminate W , obtain $\tan \alpha$
	$\alpha = 24.8^{\circ} < 26.6^{\circ} \text{ or } \frac{6}{13} < \frac{1}{2}$	A1		Comparison
	⇒ slides first	A1F	4	Conclusion; ft (b)(ii)
	Total		14	

Q Q	Solution	Marks	Total	Comments
3(a)	System is symmetrical about vertical line through <i>B</i> , hence reactions are equal	E1	1	
(b)	Resolve vertically $2R = 250$ R = 125 N	M1 A1	2	Attempt to resolve
(c)	At A resolve vertically $T_{AE} = \sin 60^{\circ} + 100 = 0$ $T_{AE} = \frac{100}{\sin 60^{\circ}} = 115.4() = 115 \text{ N}$	M1 A1		Attempt at equation involving AE $AG \left[\text{or } \frac{200\sqrt{3}}{3} \text{ seen} \right]$
	At A resolve horizontally $T_{AB} + T_{AE} \cos 60^{\circ} = 0$ $\left T_{AB} \right = \frac{100}{\sin 60^{\circ}} \times \cos 60^{\circ} = 57.73() = 57.7 \text{N}$	M1 A1	4	Attempt at equation involving AB $AG \left[\text{or } \frac{100\sqrt{3}}{3} \text{ seen} \right]$
(d)	By symmetry, $T_{BE} = T_{BD} = T$ Resolve vertically at $B: 2T \cos 30^\circ + 50 = 0$ $\left T_{BE} \right = \frac{25}{\cos 30^\circ} = 28.86 = 28.9 \text{N}$	M1 A1	3	Use of symmetry $Accept \frac{50\sqrt{3}}{3}$
	Alternative : At <i>E</i> resolve vertically			
	$R + T_{AE} \cos 30^{\circ} + T_{BE} \cos 30^{\circ} = 0$ $125 - \frac{100}{\sin 60^{\circ}} \cos 30^{\circ} + T_{BE} \cos 30^{\circ} = 0$ $ T_{BE} = 28.86 = 28.9 \text{N}$	(M1) (A1) (A1)	(3)	3 term equation involving R , T_{AE} , T_{BE} Correct equation, \pm -signs and values correct Accept $\frac{50\sqrt{3}}{3}$
(e)	At E resolve horizontally $T_{ED} + T_{BE} \cos 60^{\circ} = T_{AE} \cos 60^{\circ}$ $ T_{ED} = \frac{25}{\cos 30^{\circ}} \cos 60^{\circ} - \frac{100}{\sin 60^{\circ}} \cos 60^{\circ} = 43.3() = 43.3N$	M1 A1		3 term equation including T_{ED} , T_{BE} , T_{AE} Correct equation, \pm signs and values correct
	= 43.3N	A1F	3	Follow through T_{AE} ; accept $\frac{75\sqrt{3}}{3}$
	Total		13	

Q Q	Solution	Marks	Total	Comments
4(a)	$MI_{DISC} = \frac{1}{2}mr^2 = \frac{1}{2}(1.5)(0.2)^2$	M1		Use of $\frac{1}{2}mr^2$
	$= 0.03 \mathrm{kg} \mathrm{m}^2$	A1	2	AG
(b)(i)	$V = r\omega$ hence $2 = 0.2\omega$	M1		
	$\omega = 10 \text{ rad s}^{-1}$	A1	2	Attempt to use $r\omega$
(ii)	KE gained by pulley = $\frac{1}{2}I\omega^2$			
	$=\frac{1}{2}(0.03)(10)^2$	M1		Attempt at KE for pulley
	= 1.5 J	A1		Correct KE for pulley
	Conservation of energy: Gain $KE_{PULLEY} + KE_{BUCKET}$ = loss in PE for bucket			
	$1.5 + \frac{1}{2}(1)(2)^2 = 1gd$	M1		3 term equation
	$d = \frac{5}{14}$	A1	4	AG
(iii)	$g - T = 0.2\ddot{\theta}$	M1A1		Equation of motion for bucket $mg - T = mr\ddot{\theta}$
	$0.2T = 0.03\ddot{\theta}$	M1A1		Equation of motion for pulley $rT = I\ddot{\theta}$ A1 for correct substitutions in each case
	$0.2T = \frac{0.03(9.8 - T)}{0.2}$			
	$T = 4.2 \mathrm{N}$	A1	5	CAO
	Alternative:			
	$a = r\ddot{\theta} \implies \ddot{\theta} = \frac{a}{0.2}$	(M1)		Connecting $a, \ddot{\theta}$
	For bucket $u = 0$, $v = 2$, $s = \frac{5}{14}$			
	using $v^2 = u^2 + 2as$ gives $a = \frac{28}{5} = 5.6$			
	$\Rightarrow \ddot{\theta} = \frac{5.6}{0.2} = 28 \text{ rad s}^{-1}$	(A1)		
	Either $g - T = 0.2\ddot{\theta}$ or $0.2T = 0.03\ddot{\theta}$	(M1A1)		One other equation
	$T = 4.2 \mathrm{N}$	(A1)	(5)	CAO
	Total		13	

Q	Solution	Marks	Total	Comments
5(a)	$ \begin{array}{c c} & & & & & & \\ & & & & & & \\ & & & & $			
	Moments about <i>O</i> : -3(2) - a(6) + 2a(3) - 4(5) + 8(2) = -6 - 6a + 6a - 20 + 16 $= -10 \Rightarrow \text{ no '}a' \Rightarrow \text{ independent}$ Magnitude = 10	M1 A2,1 A1 A1F	5	One correct F×d pairing seen -1 each type of error 'a' cancels / comment about no 'a' Must be positive value stated; ft single slip
	Alternative: $ \mathbf{r}_{1} \times \mathbf{F}_{1} = \begin{vmatrix} \mathbf{i} & -1 & -8 \\ \mathbf{j} & 2 & 0 \\ \mathbf{k} & 0 & 0 \end{vmatrix} = \begin{pmatrix} 0 \\ 0 \\ 16 \end{pmatrix} $ $ \mathbf{r}_{2} \times \mathbf{F}_{2} = \begin{vmatrix} \mathbf{i} & 2 & a \\ \mathbf{j} & 6 & -3 \\ \mathbf{k} & 0 & 0 \end{vmatrix} = \begin{pmatrix} 0 \\ 0 \\ -6 - 6a \end{pmatrix} $ $ \mathbf{r}_{3} \times \mathbf{F}_{3} = \begin{vmatrix} \mathbf{i} & 3 & -4 \\ \mathbf{j} & -5 & 2a \\ \mathbf{k} & 0 & 0 \end{vmatrix} = \begin{pmatrix} 0 \\ 0 \\ 6a - 20 \end{pmatrix} $	(M1) (A1)		One correct $\mathbf{r} \times \mathbf{F}$ seen Second $\mathbf{r} \times \mathbf{F}$ correct
	Total moment = $16-6-6a+6a-20$ = -10 'a' cancels / no 'a' Magnitude = 10	(A1) (A1) (A1F)	(5)	$\sum (k \text{ components})$ Comment about 'a' ft single slip Substitute $a = 4$ and add forces
(b)(i) (ii)	$\mathbf{F} = \begin{pmatrix} 4 \\ -3 \end{pmatrix} + \begin{pmatrix} -4 \\ 8 \end{pmatrix} + \begin{pmatrix} -8 \\ 0 \end{pmatrix} = \begin{pmatrix} -8 \\ 5 \end{pmatrix}$ Moments about O : $-10 = 5d$	A1	2	y-component $\times d$ = answer (a)
	d = -2 Total	A1F	9	ft (a)

Q ((a)	Solution	Marks	Total	Comments
6(a)	Let density = ρ $m = \frac{4}{3}\pi r^3 \rho \Rightarrow \rho = \frac{3m}{4\pi r^3}$	B1		ho , m linked anywhere
	Mass of elemental disc / cylinder $= \pi (r^2 - x^2) \delta x \rho$	M1		Attempt to use $\pi r^2 h \rho$
	MI of elemental disc = $\frac{1}{2} \left[\pi \left(r^2 - x^2 \right) \delta x \rho \right] \left[r^2 - x^2 \right]$	A1		Use of $\frac{1}{2}mr^2$
	MI of sphere = $\int_{-r}^{r} \frac{1}{2} \pi \rho (r^2 - x^2)^2 dx$			
	$= \frac{3m}{8r^3} \int_{-r}^{r} \left(r^4 + x^4 - 2r^2x^2\right) dx$	m1		Attempt at integral, dep on first M1
	$= \frac{3m}{8r^3} \int_{-r}^{r} \left[r^4 x + \frac{x^5}{5} - 2r^2 \frac{x^3}{3} \right]$	A1F		Their expression integrated correctly – correct number of terms only
	$= \frac{3m}{8r^3} \left[2\left(r^5 + \frac{r^5}{5} - \frac{2r^5}{3}\right) \right]$			Correct limit used, ρ replaced to obtain answer given
	$=\frac{3m}{4r^3} \times \frac{8r^5}{15} = \frac{2}{5}mr^2$	A1	6	AG
	Alternative: Let density = ρ $m = 4\pi r^3 \rho$ $\Rightarrow \rho = \frac{3m}{4\pi r^3}$	(B1)		ρ , m linked anywhere
	Mass of elemental shell = $4\pi x^2 \delta x \rho$	(M1)		Attempt to use surface area of sphere $\times \delta x \times \rho$
	MI of elemental shell about diameter $= \frac{2}{3} (4\pi x^2 \delta x \rho) x^2$	(A1)		Use of $\frac{2}{3}mr^2$
	MI of sphere = $\int_{0}^{r} \frac{8}{3} \pi x^{4} \rho dx$			
	$=\frac{2m}{r^3}\int\limits_0^r x^4\mathrm{d}x$	(m1)		Attempt at integral; dep on first M1
	$=\frac{2m}{r^3}\int_0^r \left[\frac{x^5}{5}\right]$	(A1F)		Their expression integrated correctly
	$=\frac{2mr^5}{5r^3}$			Correct limits used, ρ replaced
	$=\frac{2mr^2}{5}$	(A1)	(6)	AG

O O	Solution	Marks	Total	Comments
6(b)(i)	$MI_{ROD} = \frac{4}{3}(3m)(2l)^2 = 16ml^2$	B1	1	Use of $\frac{4}{3}ml^2$ with 'm' = 3m and 'l' = 2l
(ii)	$MI_{SPHERE (about G)} = \frac{2}{5} (5m)(l)^2 = 2ml^2$	B1		Use of $\frac{2}{5}ml^2$ with 'm' = 5m and 'l' = l
	$MI_{SPHERE (about P)} = 2ml^2 + 5m(5l)^2$	M1		Use of parallel axis theorem
	$=127ml^2$	A1		
	$I_{PENDULUM} = 127ml^2 + 16ml^2 = 143ml^2$	A1	4	AG
(iii)	Angular momentum of clay before collision = $mv(3l) = 3mvl$ Angular momentum for pendulum after	В1		
	collision = $I_1\omega = 143ml^2\omega$	B1		Correct for pendulum
	Angular momentum for clay after collision = $I_2\omega = m(3l)^2\omega$	B1		Correct for clay
	Conservation of angular momentum: $3mvl = 143ml^2\omega + 9ml^2\omega$ $3mvl = 152ml^2\omega$	M1A1		Attempt at conservation of momentum
	$\omega = \frac{3v}{152l}$	A1F	6	ft one slip
	Total		17	
	TOTAL		75	