## ADVANCED GCE UNIT <br> MATHEMATICS (MEI)

Numerical Computation

## FRIDAY 22 JUNE 2007

## Additional materials:

Answer booklet (8 pages)
Graph paper
MEI Examination Formulae and Tables (MF2)

## INSTRUCTIONS TO CANDIDATES

- Write your name, centre number and candidate number in the spaces provided on the answer booklet.
- Answer any three questions.
- Additional sheets, including computer print-outs, should be fastened securely to the answer booklet.


## COMPUTER RESOURCES

- Candidates will require access to a computer with a spreadsheet program and suitable printing facilities during the examination.


## INFORMATION FOR CANDIDATES

- The number of marks is given in brackets [ ] at the end of each question or part question.
- In each of the questions you are required to write spreadsheet routines to carry out various numerical analysis processes. You should note the following points.
- You will not receive credit for using any numerical analysis functions which are provided within the spreadsheet. For example, many spreadsheets provide a solver routine; you will not receive credit for using this routine when asked to write your own procedure for solving an equation.
You may use the following built-in mathematical functions: square root, sin, cos, tan, arcsin, arccos, arctan, In, exp.
- For each question you attempt, you should submit print-outs showing the spreadsheet routine you have written and the output it generates. It will be necessary to print out the formulae in the cells as well as the values in the cells.
You are not expected to print out and submit everything your routine produces, but you are required to submit sufficient evidence to convince the examiner that a correct procedure has been used.
- The total number of marks for this paper is 72 .


## ADVICE TO CANDIDATES

- Read each question carefully and make sure you know what you have to do before starting your answer.
- You are advised that an answer may receive no marks unless you show sufficient detail of the working to indicate that a correct method is being used.

|  | This document consists of 4 printed pages. |  |
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1 (i) The iterative sequence $x_{0}, x_{1}, x_{2}, \ldots$, where $x_{r+1}=\mathrm{g}\left(x_{r}\right)$, has a fixed point $\alpha$, so that $\alpha=\mathrm{g}(\alpha)$. Given that $x_{r+1}-\alpha \approx k\left(x_{r}-\alpha\right)$, show that

$$
k \approx \frac{\left(x_{2}-x_{1}\right)}{\left(x_{1}-x_{0}\right)},
$$

and obtain an approximate equation for $\alpha$ in terms of $x_{2}, x_{1}$ and $k$.
(ii) Use a spreadsheet to demonstrate graphically that the equation $x=\mathrm{f}(x)$ where

$$
\mathrm{f}(x)=\mathrm{e}^{\frac{1}{3} x}+\mathrm{e}^{-\frac{1}{3} x}-0.5
$$

has two roots. Let these roots be $\alpha$ and $\beta$ where $\alpha<\beta$.
Show that the iteration $x_{r+1}=\mathrm{f}\left(x_{r}\right)$ will converge only slowly to $\alpha$ and that it will not converge to $\beta$ at all.
(iii) Use the acceleration technique developed in part (i) to speed up the convergence to $\alpha$. Find $\alpha$ correct to 6 decimal places.

Show that, with a carefully chosen starting point, the acceleration technique may be used to produce convergence to $\beta$. Find $\beta$ correct to 6 decimal places.

Determine, correct to 1 decimal place, the range of starting values for which convergence to $\beta$ is assured within 5 iterations of the acceleration technique.

2 The Gaussian 4-point integration formula has the form

$$
\int_{-h}^{h} \mathrm{f}(x) \mathrm{d} x=a \mathrm{f}(-\alpha)+b \mathrm{f}(-\beta)+b \mathrm{f}(\beta)+a \mathrm{f}(\alpha) .
$$

(i) Obtain the four equations that determine $a, b, \alpha$ and $\beta$, showing that one of them is

$$
\begin{equation*}
a \alpha^{6}+b \beta^{6}=\frac{1}{7} h^{7} . \tag{7}
\end{equation*}
$$

You are now given the following values, correct to 8 decimal places.

$$
\begin{aligned}
& a=0.34785485 h \\
& b=0.65214515 h \\
& \alpha=0.86113631 h \\
& \beta=0.33998104 h
\end{aligned}
$$

(ii) Use a spreadsheet to show that, for $x$ in radians, $\frac{\sin x}{x}$ tends to 1 as $x$ tends to 0 . Use a spreadsheet to obtain a sketch of the function $\mathrm{f}(x)=\frac{\sin x}{x}$ for $0 \leqslant x \leqslant \pi$.

Taking $h=\frac{1}{2} \pi$ initially, use the Gaussian 4-point rule to estimate the value of

$$
\int_{0}^{\pi} \frac{\sin x}{x} \mathrm{~d} x .
$$

Repeat the process, halving $h$ as necessary, in order to establish the value of the integral correct to 6 decimal places.
(iii) Modify the routines used in part (ii) to determine the value of $t$, correct to 3 decimal places, such that

$$
\begin{equation*}
\int_{0}^{t} \frac{\sin x}{x} \mathrm{~d} x=1 \tag{4}
\end{equation*}
$$

3 The differential equation

$$
\frac{\mathrm{d} y}{\mathrm{~d} x}=x+0.1 \mathrm{e}^{y}
$$

where $y=0$ when $x=0$, is to be solved in order to estimate $y$ when $x=1$.
(i) Use Euler's method with $h=0.2,0.1,0.05,0.025$ to obtain a sequence of estimates of $y$ when $x=1$. Hence demonstrate that Euler's method has first order convergence.
(ii) Show similarly that the modified Euler method has second order convergence.
(iii) Develop a solution to the differential equation using a predictor-corrector method. Use Euler's method as the predictor and the modified Euler method as the corrector. Apply the corrector 3 times at each step.

Compare the accuracy of this method with that of the modified Euler method.
(iv) Obtain a sequence of estimates of $y$ when $x=1$ by averaging the estimates found in parts (ii) and (iii). Show that this sequence appears to have approximately third order convergence.

4 The augmented matrix given below is denoted by $\mathbf{M} \mid \mathbf{c}$.

$$
\left(\begin{array}{llll|l}
0 & 1 & 2 & 3 & 1 \\
3 & 0 & 1 & 2 & 2 \\
2 & 3 & 0 & 1 & 3 \\
1 & 2 & 3 & 0 & 4
\end{array}\right)
$$

(i) Set up a spreadsheet using Gaussian elimination to solve the system of equations represented by $\mathbf{M} \mid \mathbf{c}$. Make clear at each stage which element is used for pivoting and explain why. Show how to check the accuracy of your solution.
(ii) Apply the routine developed in part (i) to systems of the form $\mathbf{M} \mid \mathbf{v}$, for appropriate vectors $\mathbf{v}$ so as to find the inverse of the matrix $\mathbf{M}$.
(iii) Use part (i) to obtain the determinant of $\mathbf{M}$, making it clear how you establish its sign.

